

# The Bellows Theorem (Introduction)



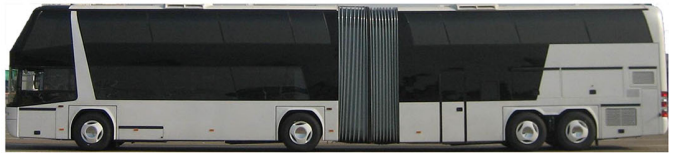
Giovanni Viglietta

JAIST – June 26, 2018

# Real-life bellows



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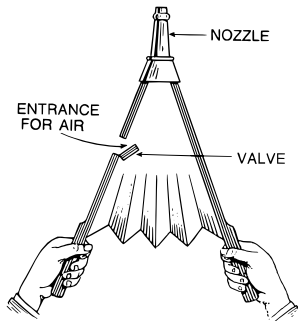


**Observation:** All of them have elasticity or curved creases. Why?

# Definition of bellows

## Wiktionary:

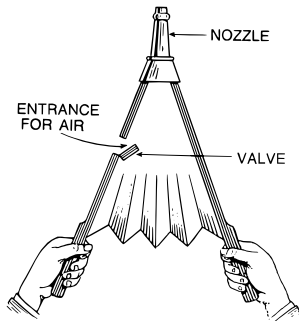
“A bellows is a container which is deformable in such a way as to alter its volume, which has an outlet where one wishes to blow air.”



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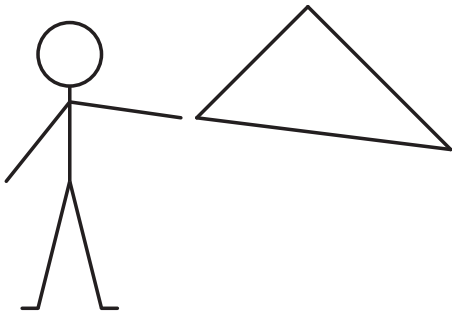
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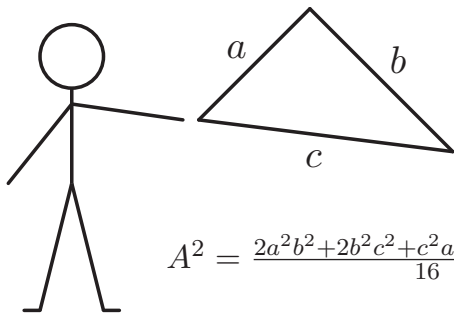
**Problem:** Is it possible to construct a “geometric bellows” in some mathematical sense?

# Bellows in Flatland



A triangular linkage (rigid bars and joints) cannot be a bellows.

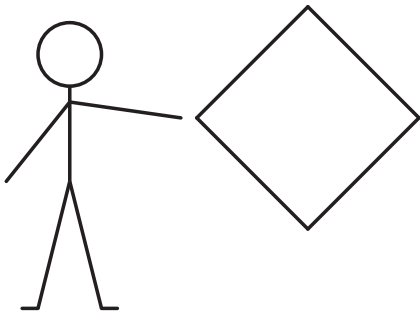
# Bellows in Flatland



$$A^2 = \frac{2a^2b^2 + 2b^2c^2 + c^2a^2 - a^4 - b^4 - c^4}{16}$$

Heron's formula gives its area as a function of the edge lengths.

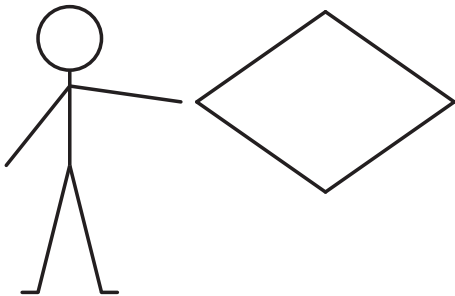
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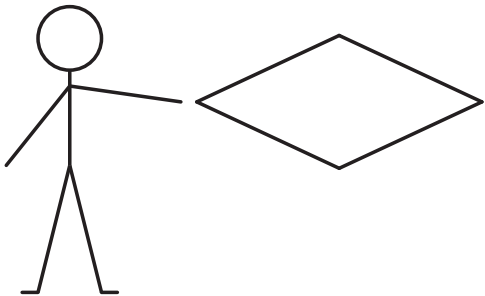


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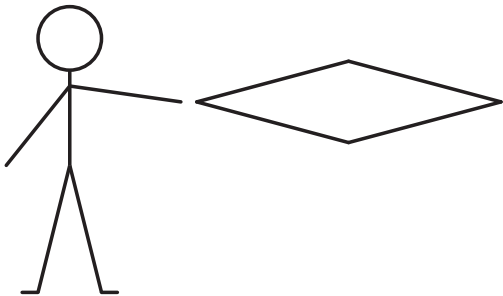
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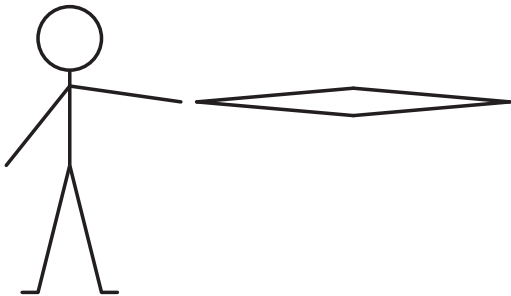
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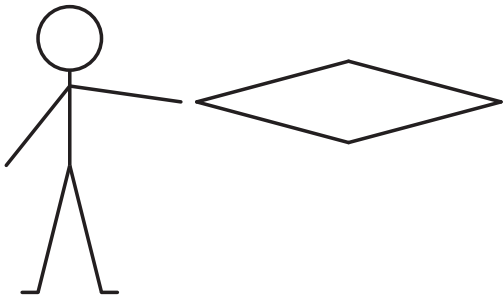
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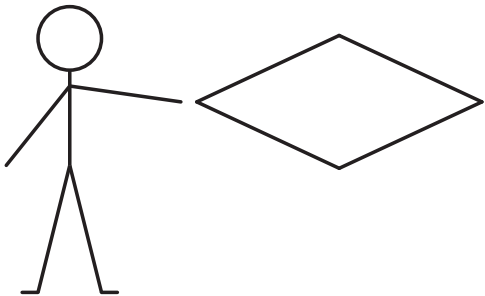
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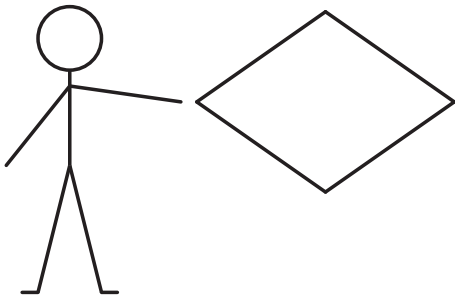
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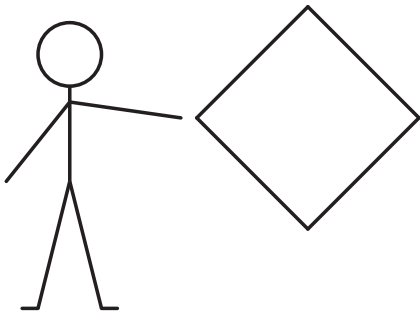
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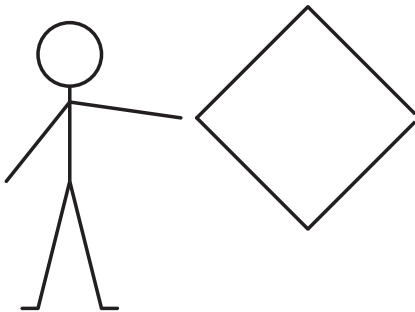
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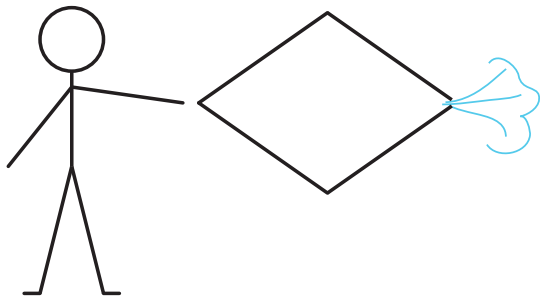


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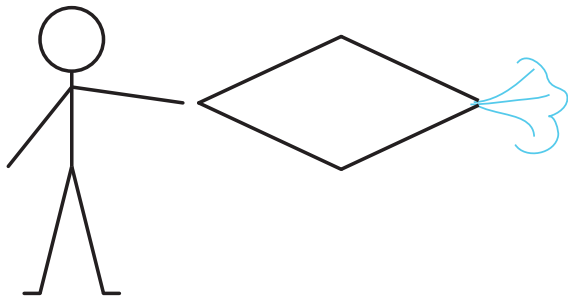
If the linkage has a small hole, it can “breathe” air as it flexes.

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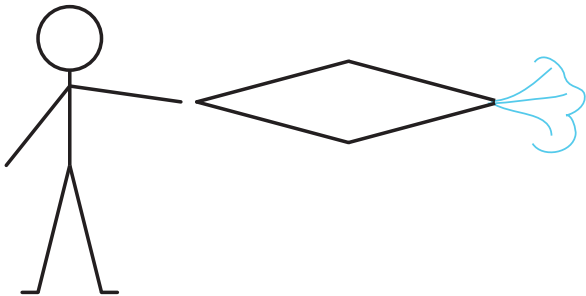
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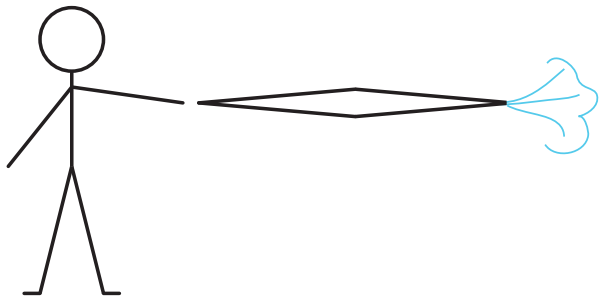
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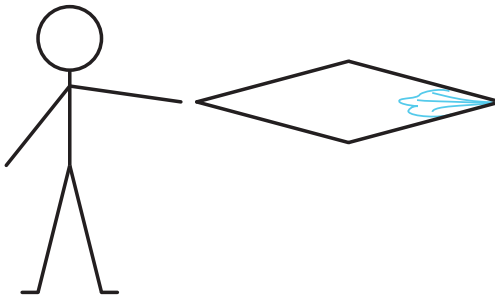
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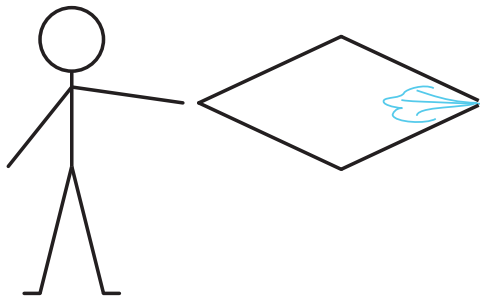
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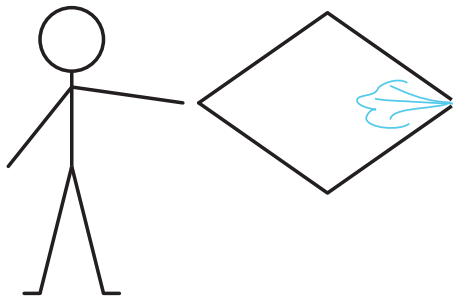
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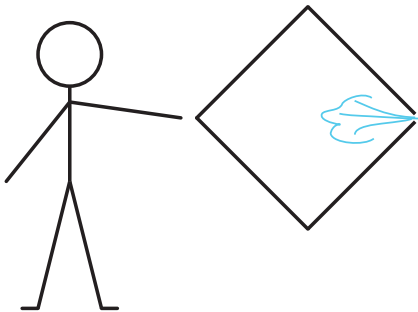
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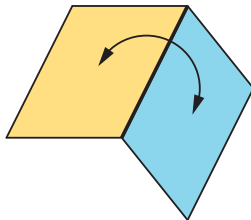
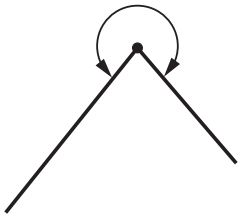
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# Polyhedral model

To define a 3D model, let us generalize 2D linkages.

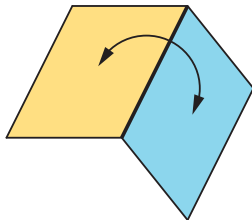
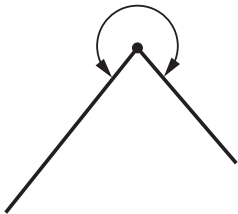


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To define a 3D model, let us generalize 2D linkages.



Instead of rigid bars, we have rigid polygons.

Instead of joints at vertices, we have hinges at edges.

**Problem:** Can such a polyhedron be a bellows? Can it even flex?

# Euclid's "definition" of equal polyhedra

## **Euclid's Elements, Book XI, Definition 10:**

ι'. Ἴσα δὲ καὶ ὅμοια στερεὰ σχήματά ἐστι τὰ ὑπὸ ὁμοίων ἐπιπέδων περιεχόμενα ἴσων τῷ πλήθει καὶ τῷ μεγέθει.

### **Literal translation:**

Equal and similar solid figures are those contained by similar planes equal in multitude and in magnitude.

### **Modern interpretation:**

Two polyhedra are equal if they have the same combinatorial structure and equal corresponding faces.

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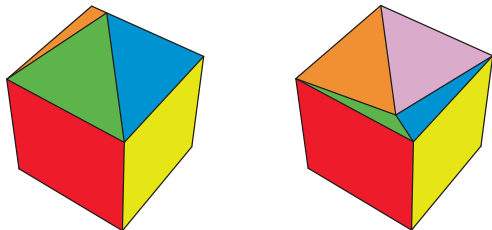
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⇒ Euclid seems to disallow the existence of flexible polyhedra!

# Simson's critique to Euclid

**Simson, 1756:** Euclid's statement cannot be a definition, but a theorem that ought to be proved.

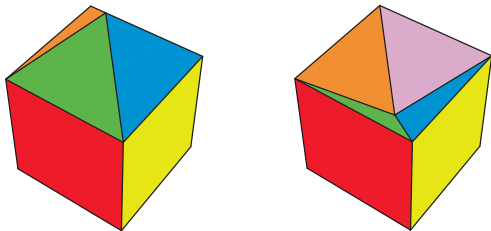
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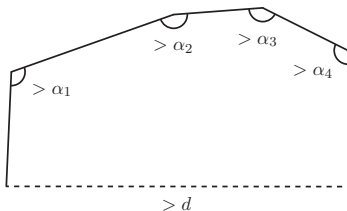
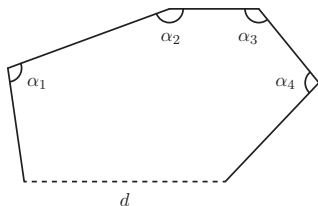


**Heath, 1908:** To be fair, Euclid only applies his definition to prove equality of convex polyhedra with trihedral vertices.

For these polyhedra, Euclid's statement is obviously true, because a trihedral vertex is rigid.

# Convex polyhedra are rigid

## Cauchy's arm lemma:



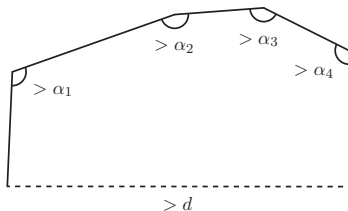
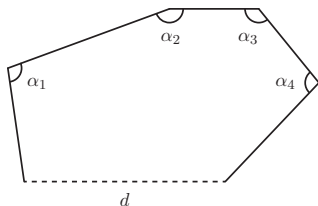
## Theorem (Legendre-Cauchy, 1813)

*Two convex polyhedra are equal if they have the same combinatorial structure and equal corresponding faces.*



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## Corollary

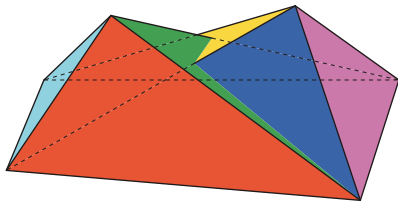
*Convex polyhedra are rigid.*

$\implies$  Polyhedral bellows must be non-convex.

# Existence of flexible polyhedra

Theorem (Bricard, 1897)

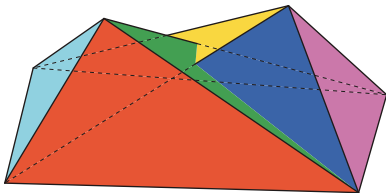
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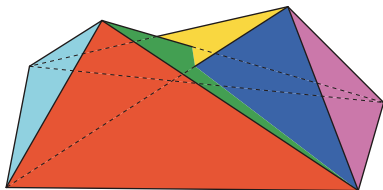
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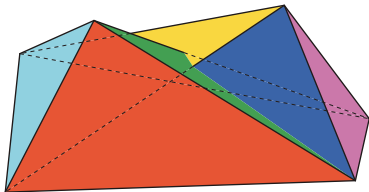
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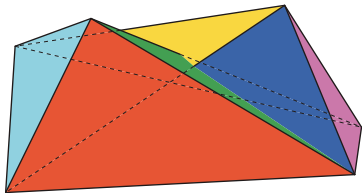
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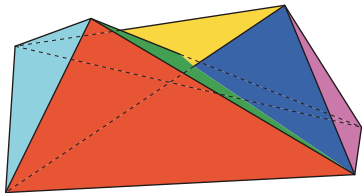
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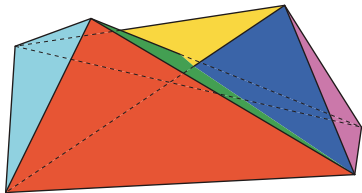
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*Almost all polyhedra of genus 0 are rigid.*

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Theorem (Connelly, 1977)

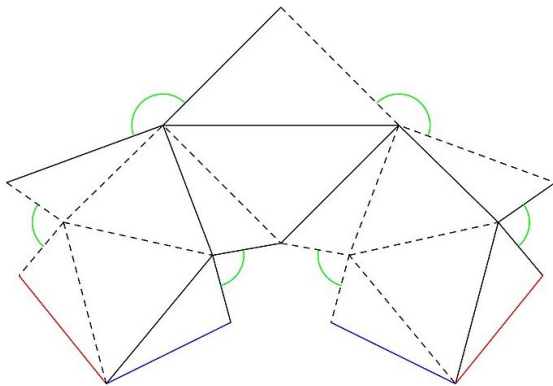
*There exist (non-self-intersecting) flexible polyhedra.*



# Steffen's flexible polyhedron

Theorem (Steffen, 1979)

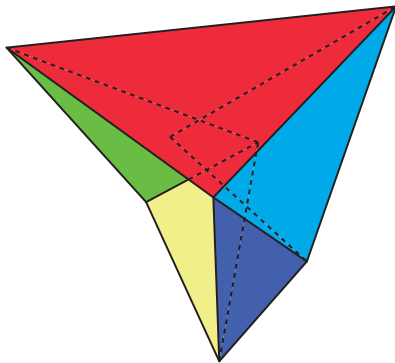
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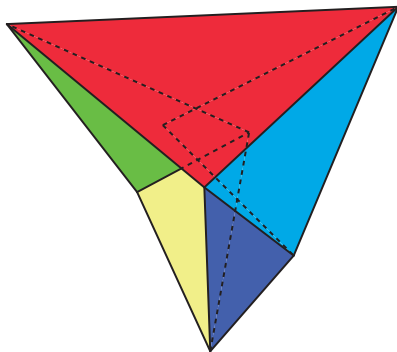
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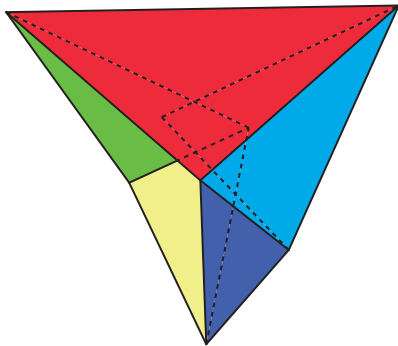
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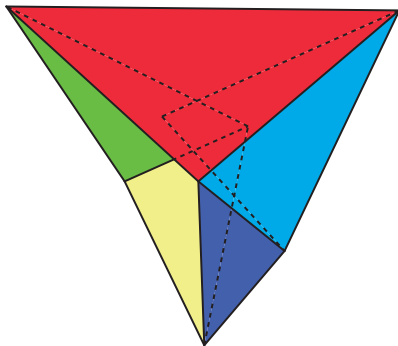
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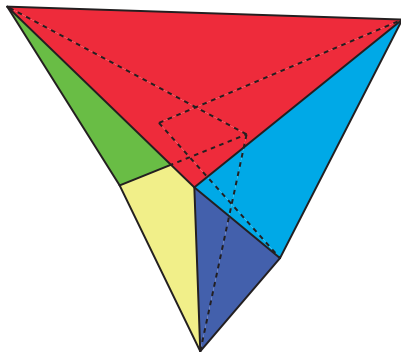
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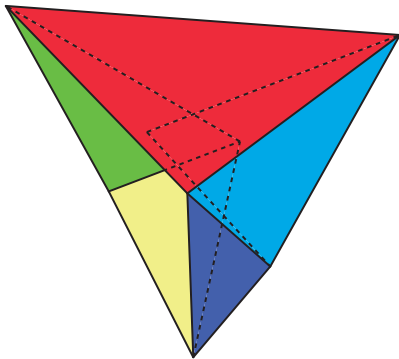
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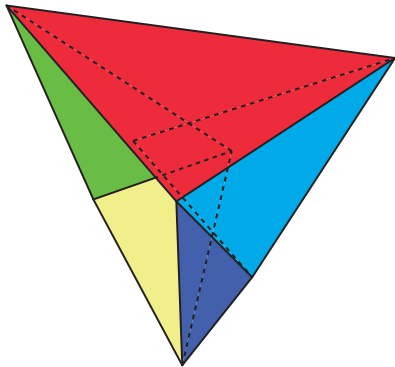
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## Observation

*The (generalized) volume of all these flexible polyhedra remains constant throughout the flexing!*

*In other words, although these polyhedra are not rigid, none of them can blow air.*

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*The (generalized) volume of all these flexible polyhedra remains constant throughout the flexing!*

*In other words, although these polyhedra are not rigid, none of them can blow air.*

Several people made the conjecture that this is not a coincidence, and Connelly coined a name for it:

## Bellows conjecture (Connelly, 1978)

*The volume of a polyhedron is constant throughout any flexing. In other words, there are no polyhedral bellows.*

## Theorem (Sabitov, 1996)

*Given a polyhedron (of any genus), its volume  $V$  satisfies*

$$V^N + a_{N-1}(\bar{\ell})V^{N-1} + \dots + a_1(\bar{\ell})V + a_0(\bar{\ell}) = 0,$$

*where the coefficients  $a_i(\bar{\ell})$  only depend on the combinatorial structure of the polyhedron and on the lengths of its edges,  $\bar{\ell}$ .*

# Bellows theorem

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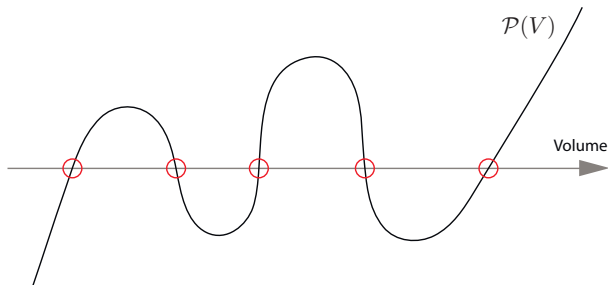
The volume is a root of a polynomial that remains fixed as the polyhedron flexes, hence it can only take finitely many values.

## Corollary (Bellows theorem)

*The volume of a polyhedron is constant throughout any flexing.*

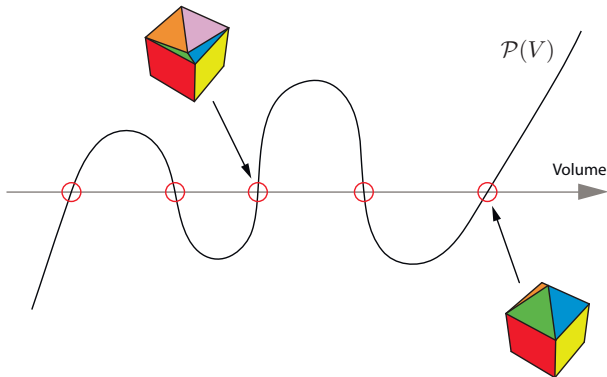
$\implies$  There are no polyhedral bellows (of any genus).

# Bellows theorem



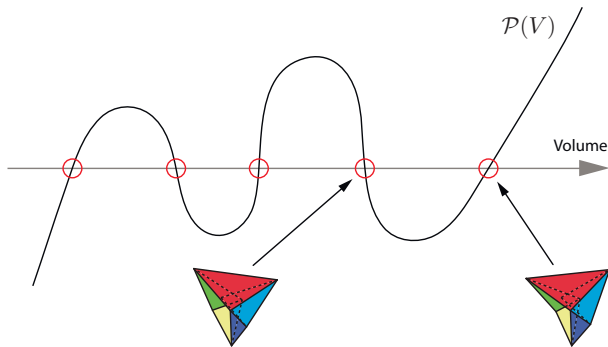
Any polynomial has a finite number of roots:  
at most as many as its degree.

# Bellows theorem



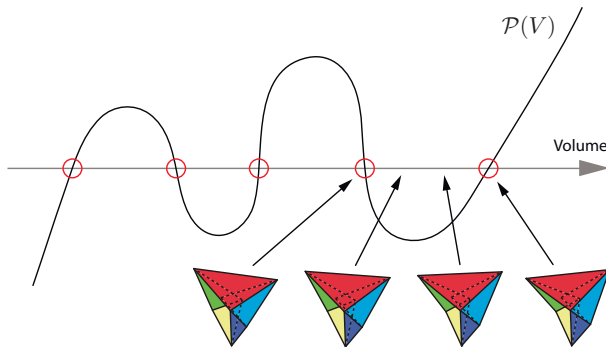
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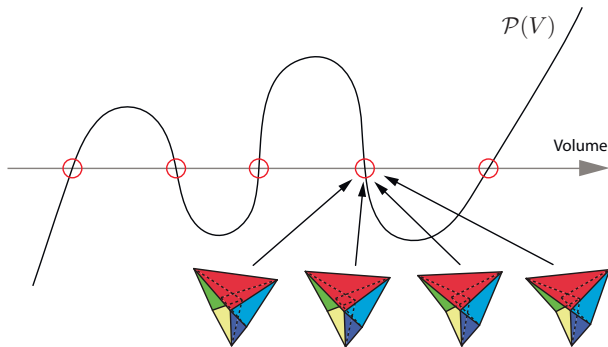
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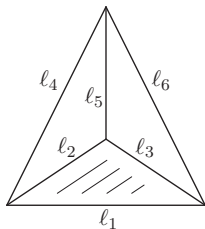
## Example: tetrahedra

There is an analogue of Heron's formula for tetrahedra:

**Theorem (Piero della Francesca, 15th century)**

*The volume  $V$  of a tetrahedron with edges  $l_1, \dots, l_6$  satisfies*

$$V^2 = \frac{1}{144} [l_1^2 l_5^2 (l_2^2 + l_3^2 + l_4^2 + l_6^2 - l_1^2 - l_5^2) + l_2^2 l_6^2 (l_1^2 + l_3^2 + l_4^2 + l_5^2 - l_2^2 - l_6^2) + l_3^2 l_4^2 (l_1^2 + l_2^2 + l_5^2 + l_6^2 - l_3^2 - l_4^2) - l_1^2 l_2^2 l_3^2 - l_2^2 l_4^2 l_5^2 - l_1^2 l_4^2 l_6^2 - l_3^2 l_5^2 l_6^2]$$



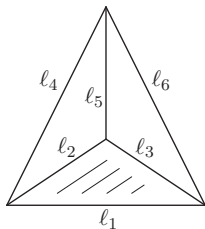
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The polynomial equation has the form  $\mathcal{P}(V) = V^2 + a_0(\bar{l}) = 0$ .

Theorem (Gaifullin, 2012)

*The bellows theorem generalizes to any dimension  $> 3$ .*

# Generalizations and extensions

## Theorem (Gaifullin, 2012)

*The bellows theorem generalizes to any dimension  $> 3$ .*

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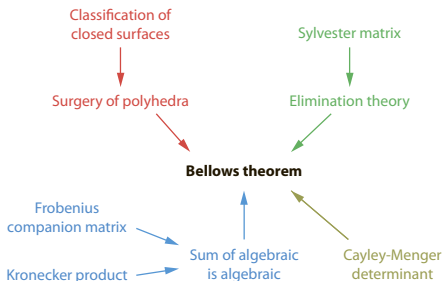
*Wrong?*

## Theorem (Gaifullin-Ignashchenko, under review)

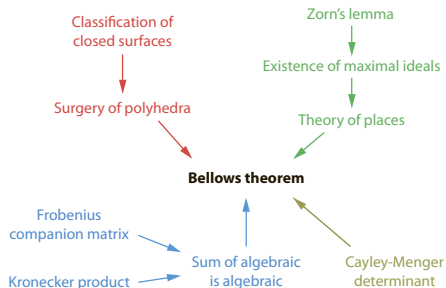
*A polyhedron preserves its Dehn invariant throughout any flexing.  
Hence the strong bellows conjecture is true. (cf. Sydler, 1965)*

# Next seminar: proving the bellows theorem

## Geometric approach



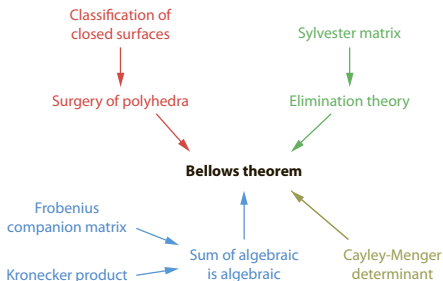
## Algebraic approach



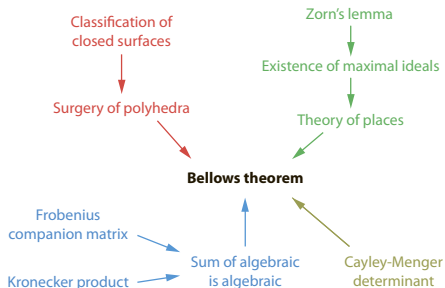


# Next seminar: proving the bellows theorem

## Geometric approach



## Algebraic approach



### Pros:

- Volume polynomial explicitly constructed
- Self-contained proof (given basic linear algebra and topology)

### Cons:

- Some cumbersome computations

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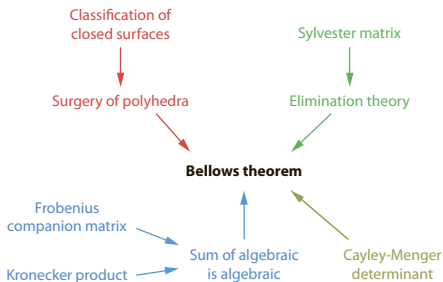
- Non-constructive proof
- Heavier on theory (valuation rings, extension of homomorphisms, ...)

### Pros:

- Elegant proof

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## Geometric approach



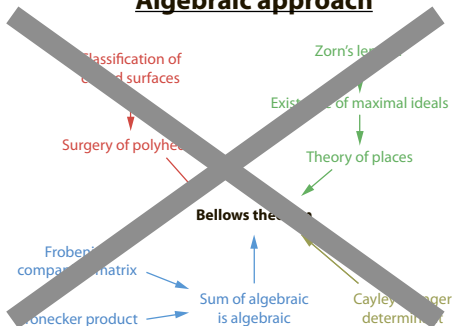
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### Pros:

- Elegant proof

## Determinant of a square matrix:

- Basic properties, e.g.,  $\det(AB) = \det(A) \det(B)$
- How to compute it, especially by Laplace expansion
- Usage in linear algebra:  $A$  is invertible iff  $\det(A) \neq 0$
- Geometric interpretation: scaling factor of the linear transformation described by the matrix

## Eigenvalues of a square matrix:

- Definition and basic properties
- Relationship with the characteristic polynomial of the matrix

## Closed orientable surfaces:

- Geometric intuition of genus: number of holes
- Topological intuition of surgery: what happens when a circular cut is made on a closed orientable surface